Disclaimer

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Introduction
Value
Availability
Deployment
Sparsity & Performance
Scale
Q&A

What is Anaplan Polaris?

What is Polaris?

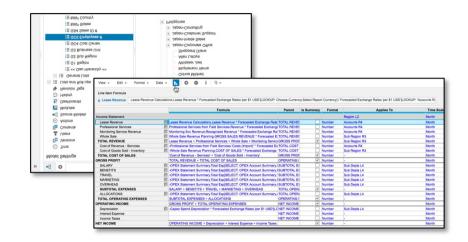
- Polaris is a new underlying storage and calculation engine for Anaplan. It is a natively sparse engine – designed as a general purpose planning and modelling engine for naturally sparse business problems.
- It will work side by side with the existing 'Classic' engine on a workspace by workspace basis. A workspace will either be a 'Classic Workspace' or a 'Polaris Workspace'.
- The main advantages of a natively sparse engine is that it allows much higher dimensionality and granularity for sparse business problems.

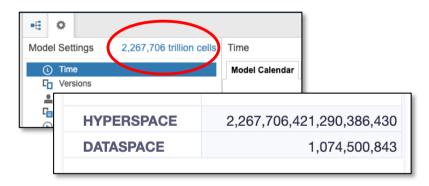
Anaplan Polaris

The same Anaplan modelling interface you currently use...

 With a new underlying storage and calculation engine...

 Allowing massive dimensionality – more dimensions and / or more items in a dimension





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What value does Anaplan Polaris bring?

With Anaplan Polaris, businesses can...



- Solve business problems by modeling data in its natural state
- Analyze multiple intersections of highly sparse data for more granular insight
- Expand data dimensionality of list items to plan and scale with business



- Empower business users to slice and dice data for in-depth analysis and reporting
- Eliminate the need to concatenate or/and flatten data structures, hierarchies, split models (by regions, for example) for an intuitive user experience



- ✓ CAPEX: Consolidate the software estate by reducing or eliminating multiple planning and analysis tools
- OPEX: Reduce the extra resources and time needed to manage and maintain multiple tools

When will Polaris be available and what functionality is supported?

Polaris Release Availability



■ LA – Phase I

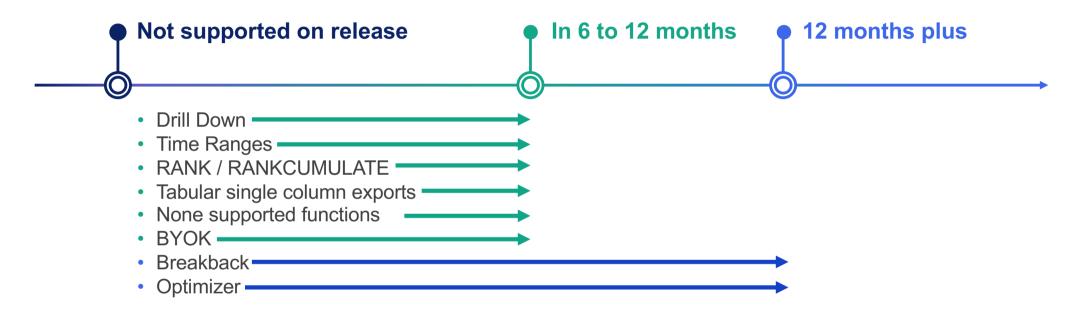
LA – Phase II

GA

- Open to EA customers
- Requires an Anaplan Solution Architect to support the project
- Supported by the cross functional Polaris launch team
- Based on assessment of the suitability of the use case
- Requires an Anaplan Solution Architect to support the project
- Supported by the cross functional Polaris launch team
- Available for all customers

Functionality Support





Notes:

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^{*} Details for non-supported calculation functions here

How is Polaris Deployed?

How is Polaris deployed.

- When created, a Workspace is set to be either 'Classic' or 'Polaris'
- Once created, the type of a workspace cannot be changed.
- To create a Polaris model, you simply create a new model in the Polaris workspace.
- It is possible to import/export between models in different types of workspace
- It is possible to copy Model Structure (via a Model Import) provided that only features supported in Polaris are used in the source model

Performance, Populated Cells, and Sparsity

Performance

- The performance of a sparse engine is based on how the data is stored and organized and which results are calculated.
- Polaris performance is based on only storing combinations that hold data and only calculating combinations that may be relevant and generate results.
- To understand this, we need to explain
 - Sparsity & Density
 - Default Values
 - Calculation Complexity

Naming and Terminology

- Sparsity / Density is the ratio of populated cells to totally addressable cells. A Sparse model/module/line item is one where the vast majority of cells are not populated.
- Populated Cells A populated cell is one that does not contain the Default Value.
- Default Value The default value is currently fixed for each data type:
 - Numeric: Zero
 - Boolean: False
 - · List Item: [Blank]
 - Date: [Blank]
 - Time Period: [Blank]
 - Text: "" [An empty string]

Notes:

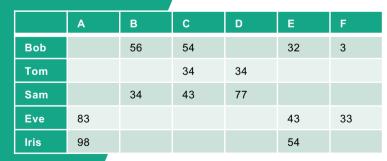
^{*} Polaris has exactly the same semantics as the Classic engine when it comes to Numerics / Null.

A Sparse Engine vs. a Dense Engine

In a Sparse Engine, only data values that are populated are stored. This is much more efficient for 'naturally sparse' data sets.

In a Dense Engine, like current Anaplan, memory is reserved for all possible data values in a coordinate space.

14 Cells with non-zero numbers stored in a Sparse Engine





All 30 Cells stored in a Dense Engine

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The Memory required for each cell is also different

For a sparse engine, for every numeric Cell stored, approximately 24 bytes is required.

In a Dense Engine, like current Anaplan, each numeric cell requires 8 bytes.

14 Cells with Values x 24 bytes = 336 bytes in a Sparse Engine



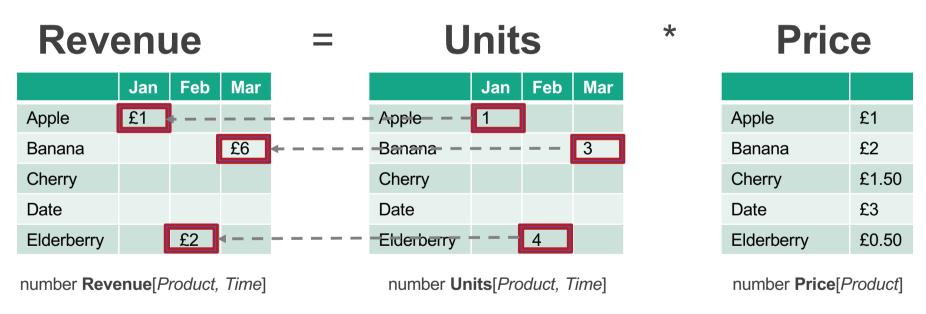
	A	В	С	D	E	F
Bob		56	54		32	3
Tom			34	34		
Sam		34	43	77		
Eve	83				43	33
Iris	98				54	



30 cells x 8 bytes = 240 bytes in a dense engine

One to One Calculations

• One-to-One formulas are where the calculation can be driven from one of the source line items in a way so that there will only ever be the same or fewer populated cells in the target line item than the sum of the input line items. A simple example is a multiplication (as we know that anything x zero is zero and therefore doesn't need to be calculated).



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'One-To-Many' Calculations

 'One-To-Many' Calculations are ones where the output can have more than the sum of populated cells in the inputs, but not every cell in the output has to be calculated. In a very simple example, if a Month dimensioned line item references a Quarter dimensioned line item, then the quarter value will be spread across the respective months. This will result in a greater number of populated cells in the target than the source.

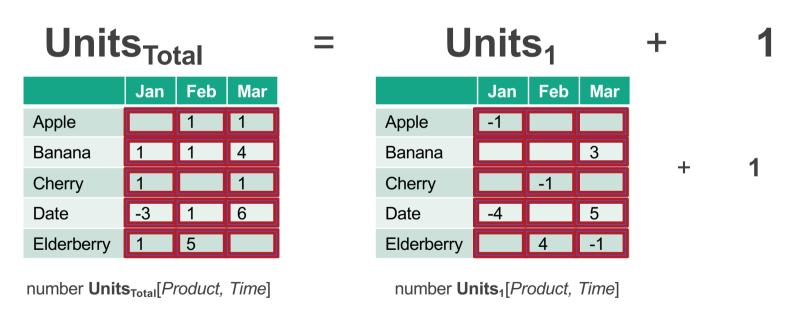
Units _{Month}				=	Units _{Quarte}			
	Jan	Feb	Mar			Q1		
Apple	4	4	4		Apple	4		
Banana	5	5	5		Banana	5		
Cherry					Cherry			
Date	1	1	1		Date	1		
Elderberry					Elderberry			
number Unit	number Units _{Total} [<i>Product, Time</i>] number Units ₁ [<i>Product, Time</i>]							

number **Units**₁|*Product, Time*|

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'All Cells' Calculations

• 'ALL Cells' formulas are where the calculation cannot be driven from any of the line item's populated cells. The only way to perform this type of calculation is to iterate over every cell in the target. A simple example is an Addition of a literal. In this case, every cell must be touched in order to calculate the result. Note that the result is not 100% Dense, but the calculation still has to iterate over every cell.



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Polaris Calculation Complexity

Formulas can be divided into 3 categories of Calculation Efficiency, depending on how they can be 'driven'

- One-to-One This is where the output will be *As Sparse* as the sources. This type of calculation maintains sparsity, and is the most efficient category of calculation type.
- One-to-Many This is where the output can be *More Dense* than the sources, but not every target cell can be populated. One-to-Many Calcs can be described using a *'Fan-Out Factor'* which describes the multiple of possible cells that can be populated.
- ALL Cells This is where every cell has to be calculated 100% Densely, and every cell could be populated. This is the least efficient type of calculation.

Scale Limitations in Polaris

Scale Limits in Polaris

There are two major scale constraints in Polaris:

- 1. The model must fit within a workspace. Just like Classic Anaplan, Polaris holds the whole model in memory within one running server. Polaris can make use of Hypermodels, but the model can't be larger than the workspace size.
- 2. The theoretical limit for a line item is 2⁶⁴ cells. This is approximately 18 quintillion cells (18 million trillion). The limit will vary depending on the shape of the dimensions, but the absolute maximum is 2⁶⁴ cells **PER LINE ITEM**.

The practical limit will always be less than this due to the representation of the dimension index. Nonetheless, a line item in Polaris can have trillions of addressable cells.

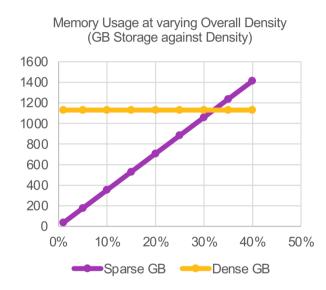


Effect of Density on Memory Use for Sparse vs Dense Engines

In a Dense engine, each numeric value requires ~8 bytes for storage. As the whole hyperspace is stored – the total storage requirement does not change with density.

In a Sparse engine, each numeric value requires ~24 bytes for storage. Only the populated values are stored.

This means that for a given model, if the overall density is >33%, a dense engine is more memory efficient, and if <33%, a Sparse engine is more efficient.



Above chart showing memory usage for Inventory Planning example against varying overall density for sparse and dense engines.

Aggregate Cells are usually not as Sparse as Primary Cells

Adding 1 level of rollup to each dimension in this example, moves the overall density from 47% to 70%

	Primary Cells	Aggregat e Cells	Total Cells	
Number of Cells	30	26	56	
Populate d	14	25	39	
Density	47%	96%	70%	

100% Dense	ABC	DEF
Men	144	69
Women	258	207

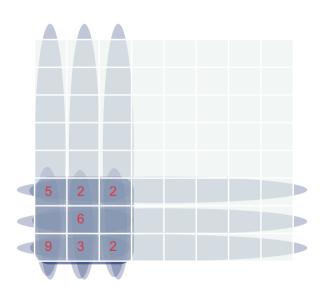


	92% Dense							
		Α	В	С	D	E	F	
	Men		56	88	34	32	3	
,	Women	181	34	43	77	97	33	

100% Dense	ABC	DEF
Bob	110	35
Tom	34	34
Sam	77	77
Eve	83	76
Iris	98	54

Primary Cells 47% dense		ABC			DEF		
		А	В	С	D	Е	F
	Bob		56	54		32	3
Men	Tom			34	34		
	Sam		34	43	77		
Women	Eve	83				43	33
	Iris	98				54	

The degree to which numbers of levels in hierarchies affect the overall density (and therefore size) of a dataspace is heavily dependent on the distribution of the data.



The same number of primary data cells can lead to very different numbers of populated roll-ups.

