2.192 UIAlphaEntry - User Alpha Entry RobotWare-OS

# 2.192 UIAlphaEntry - User Alpha Entry

Usage	UIAlphaEntry ( <i>User Interaction Alpha Entry</i> ) is used to let the operator enter a string from the available user device, such as the FlexPendant. A message is written to the operator, who answers with a text string. The string is then transferre back to the program.	
Basic examples		
	The following example illustrates the function UIAlphaEntry.	
	See More examples on page 1428.	
Example 1	VAR string answer;	
	••••	
	answer := UIAlphaEntry(	
	\Header:= "UIAlphaEntry Header",	
	\Message:= "Which procedure do You want to run?" \Icon:=iconInfo	
	<pre>\InitString:= "default_proc");</pre>	
	<pre>%answer%;</pre>	
	SED0_RW5.06_TB57_MR5         Auto         SEJ0_RW5.06_TB57_MR5(SEVS)         Auto         SEJ0_RW5.06_TB57_MR5(SEVS)         Running (1 of 3) (Speed 100%)             All tasks             T_ROB1         UIAlphaEntry             Which procedure do You want to run?             Image: Comparison of the second	
	ABC OK	
	Production T_ROB1	

xx0500002437

Above alpha message box with icon, header, message, and init string are written on the FlexPendant display. The user edit init string or write a new string with the supported Alpha Pad. Program execution waits until OK is pressed and then the

# 2 Functions

# 2.192 UIAlphaEntry - User Alpha Entry RobotWare-OS Continued

written string is returned in the variable answer. The program then calls the specified procedure with late binding.

Return value	
	Data type: string
	This functions returns the input string.
	If function breaks via \BreakFlag:
	<ul> <li>If parameter \InitString is specified, this string is returned</li> </ul>
	<ul> <li>If parameter \InitString is not specified, empty string " " is returned.</li> </ul>
	If function breaks via ERROR handler, no return value will be returned at all.
Arguments	
-	UIAlphaEntry ([\Header] [\Message] [\MsgArray] [\Wrap][\Icon][\InitString] [\MaxTime] [\DIBreak] [\DIPassive] [\DOBreak] [\DOPassive] [\BreakFlag] [\UIActiveSignal])
[\Header]	
	Data type: string
	Header text to be written at the top of the message box. Max. 40 characters.
[\Message]	
[ (	Data type: string
	One text line to be written on the display. Max 55 characters.
[\MsgArray]	
[\MSGAILay]	Message Array
	Data type: string
	Several text lines from an array to be written on the display.
	Only one of parameter \Message or \MsgArray can be used at the same time.
	Max. layout space is 9 lines with 55 characters.
[\Wrap]	Data type: switch
	If selected, all the specified strings in the argument \MsgArray will be concatenated
	to one string with single space between each individual strings and spread out on as few lines as possible.
	Default, each string in the argument \MsgArray will be on separate line on the display.
[\lcon]	
	Data type: icondata
	Defines the icon to be displayed. Only one of the predefined icons of type icondata can be used. See <i>Predefined data on page 1428</i> .
	Default no icon.
[\InitString]	
	Data type: string
Continues on next	page

An initial string to be display in the text entry box as default.

[\MaxTime]	
------------	--

### Data type: num

The maximum amount of time in seconds that program execution waits. If the OK button is not pressed within this time, the program continues to execute in the error handler unless the BreakFlag is used (see below). The constant ERR\_TP\_MAXTIME can be used to test whether or not the maximum time has elapsed.

### [\DIBreak]

### Digital Input Break

Data type: signaldi

The digital input signal that may interrupt the operator dialog. If the OK button is not pressed before the signal is set to 1 (or is already 1), the program continues to execute in the error handler, unless the BreakFlag is used (see below). The constant ERR\_TP\_DIBREAK can be used to test whether or not this has occurred.

# [\DIPassive]

# Digital Input Passive

Data type: switch

This switch overrides the default behavior when using DIBreak optional argument. Instead of reacting when signal is set to 1 (or already 1), the instruction should continue in the error handler (if no BreakFlag is used) when the signal DIBreak is set to 0 (or already is 0). The constant ERR\_TP\_DIBREAK can be used to test whether or not this has occurred.

### [\DOBreak]

# Digital Output Break

# Data type: signaldo

The digital output signal that may interrupt the operator dialog. If the OK button is not pressed before the signal is set to 1 (or is already 1), the program continues to execute in the error handler, unless the BreakFlag is used (see below). The constant ERR\_TP\_DOBREAK can be used to test whether or not this has occurred.

# [\DOPassive]

# **Digital Output Passive**

# Data type: switch

This switch overrides the default behavior when using DOBreak optional argument. Instead of reacting when signal is set to 1 (or already 1), the instruction should continue in the error handler (if no BreakFlag is used) when the signal DOBreak is set to 0 (or already is 0). The constant ERR\_TP\_DOBREAK can be used to test whether or not this has occurred.

[\BreakFlag]

Data type: errnum

# 2 Functions

# 2.192 UIAlphaEntry - User Alpha Entry RobotWare-OS Continued

A variable (before used set to 0 by the system) that will hold the error code if \MaxTime, \DIBreak or \DOBreak is used. The constants ERR\_TP\_MAXTIME, ERR\_TP\_DIBREAK and ERR\_TP\_DOBREAK can be used to select the reason. If this optional variable is omitted, the error handler will be executed.

### [\UIActiveSignal]

Data type: signaldo

The digital output signal used in optional argument <code>UIActiveSignal</code> is set to 1 when the message box is activated on the FlexPendant. When the user selection has been done and the execution continue, the signal is set to 0 again.

No supervision of stop or restart exist. The signal is set to 0 when the function is ready, or when PP is moved.

### **Program execution**

The alpha message box with alpha pad, icon, header, message lines, and init string are displayed according to the programmed arguments. Program execution waits until the user edits or creates a new string and presses OK, or the message box is interrupted by time-out or signal action. The input string and interrupt reason are transferred back to the program.

New message box on TRAP level takes focus from message box on basic level.

### **Predefined data**

```
!Icons:
  CONST icondata iconNone := 0;
  CONST icondata iconInfo := 1;
  CONST icondata iconWarning := 2;
  CONST icondata iconError := 3;
```

### More examples

The following example illustrates the function UIAlphaEntry.

### Example 1

VAR errnum err_var;
VAR string answer;
VAR string logfile;
answer := UIAlphaEntry (\Header:= "Log file name:"
\Message:= "Enter the name of the log file to create?"
\Icon:=iconInfo
\InitString:= "signal.log"
\MaxTime:=60
<pre>\DIBreak:=di5\BreakFlag:=err_var);</pre>
TEST err_var
CASE ERR_TP_MAXTIME:
CASE ERR_TP_DIBREAK:
! No operator answer
<pre>logfile:="signal.log";</pre>
CASE 0:
! Operator answer

1428

2.192 UIAlphaEntry - User Alpha Entry RobotWare-OS Continued

The message box is displayed and the operator can enter a string and press OK. The message box can also be interrupted with time out or break by digital input signal. In the program it is possible to find out the reason and take the appropriate action.

# Error handling

The following recoverable errors are generated and can be handled in an error handler. The system variable ERRNO will be set to:

Name	Cause of error
ERR_NO_ALIASIO_DEF	The signal variable is a variable declared in RAPID and it has not been connected to an I/O signal defined in the I/O configuration with instruction AliasIO.
ERR_TP_NO_CLIENT	There is no client, for example, a FlexPendant, to take care of the instruction.

If parameter \BreakFlag is not used, these situations can then be dealt with by the error handler:

If there is a time-out (parameter  $\mbox{MaxTime}$ ) before an input from the operator, the system variable ERRNO is set to ERR\_TP\_MAXTIME and the execution continues in the error handler.

If digital input is set (parameter \DIBreak) before an input from the operator, the system variable ERRNO is set to ERR\_TP\_DIBREAK and the execution continues in the error handler.

If a digital output is set (parameter \DOBreak) before an input from the operator, the system variable ERRNO is set to ERR\_TP\_DOBREAK and the execution continues in the error handler.

### Limitations

Avoid using too small a value for the time-out parameter \MaxTime when UIAlphaEntry is frequently executed, for example in a loop. It can result in an unpredictable behavior of the system performance, like slow response of the FlexPendant.

#### Syntax

```
UIAlphaEntry '('
  ['\' Header ':=' <expression (IN) of string>]
  ['\' Message ':=' <expression (IN) of string>]
  ['\' MsgArray ':='<array {*} (IN) of string>]
  ['\' Wrap]
  ['\' Icon ':=' <expression (IN) of icondata>]
  ['\' InitString ':='<expression (IN) of string>]
  ['\' MaxTime ':=' <expression (IN) of num>]
  ['\' DIBreak ':=' <variable (VAR) of signaldi>]
  ['\' DIPassive]
```

© Copyright 2004-2016 ABB. All rights reserved.

# 2 Functions

# 2.192 UIAlphaEntry - User Alpha Entry RobotWare-OS Continued

```
['\' DOBreak ':='<variable (VAR) of signaldo>]
['\' DOPassive]
['\' BreakFlag ':=' <var or pers (INOUT) of errnum>]
['\' UIActiveSignal ':=' <variable (VAR) of signaldo>] ')'
```

A function with return value of the data type string.

# **Related information**

For information about	See
Icon display data	icondata - Icon display data on page 1554
User interaction message box type basic	UIMsgBox - User Message Dialog Box type basic on page 922
User interaction message box type advanced	UIMessageBox - User Message Box type ad- vanced on page 1453
User interaction number entry	UINumEntry - User Number Entry on page 1460
User interaction number tune	UINumTune - User Number Tune on page 1466
User interaction list view	UIListView - User List View on page 1445
System connected to FlexPendant etc.	UIClientExist - Exist User Client on page 1431
Procedure call with late binding	Technical reference manual - RAPID overview
Clean up the operator window	TPErase - Erases text printed on the FlexPend- ant on page 808